



# Robot Mechanisms Intelligent Systems, Control and Automation Science and Engineering

By Jadran Lenarcic

Springer. Paperback. Condition: New. 334 pages. Dimensions: 9.2in. x 6.1in. x 0.8in. This book provides a comprehensive introduction to the area of robot mechanisms, primarily considering industrial manipulators and humanoid arms. The book is intended for both teaching and self-study. Emphasis is given to the fundamentals of kinematic analysis and the design of robot mechanisms. The coverage of topics is untypical. The focus is on robot kinematics. The book creates a balance between theoretical and practical aspects in the development and application of robot mechanisms, and includes the latest achievements and trends in robot science and technology. This item ships from multiple locations. Your book may arrive from Roseburg,OR, La Vergne,TN. Paperback.



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